

# Network Computing and Efficient Algorithms

## Maximal Independent Set

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# Outline

- 1 Maximal Independent Set (Deterministic Alg.)
- 2 Original Fast MIS (Randomized Alg.)
- 3 Fast MIS v2
- 4 Applications of Independent Set

# Maximal Independent Set

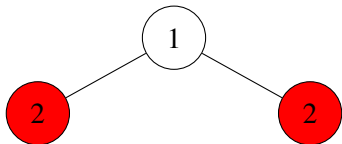
## Definition 7.1 (Independent Set)

Given an undirected Graph  $G = (V, E)$  an independent set is a subset of nodes  $U \subseteq V$ , such that no two nodes in  $U$  are adjacent. An independent set is a **maximal** if no node can be added without violating independence. An independent set of **maximum** cardinality is called maximum.

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**Figure 7.2:** Example graph with 1) a maximal independent set (MIS) and 2) a maximum independent set (MaxIS).

# Remarks

- Computing a maximum independent set (MaxIS) is equivalent to computing maximum clique on the complementary graph.
  - Both problems are NP-hard.
  - Not approximable within  $n^{0.5-\epsilon}$  within polynomial time.
- MIS and MaxIS can be quite different.
- Computing a MIS sequentially is trivial...
  - How to compute a MIS in a distributed way?

# Slow MIS

**Require:** Node IDs

**Every node**  $v$  executes the following code:

**ALGORITHM 7.3:** SLOW MIS()

- 1: **if** all neighbours of  $v$  with larger identifiers have decided not to join the MIS **then**
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**Not better than the sequential algorithm in the worst case!**



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- In the first round all nodes of the first color join the MIS and notify their neighbors.
- Then, all nodes of the second color which do not have a neighbor that is already in the MIS join the MIS and inform their neighbors.
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- This process is repeated for all colors.

## Corollary 7.5

Given a coloring algorithm that runs in time  $T$  and needs  $C$  colors we can construct a MIS in time  $T + C$

# Fast MIS

The algorithm operates in synchronous rounds, grouped into phases.

**A single phase** is as follows:

**ALGORITHM 7.6:** FAST MIS()

- 1: Each node  $v$  marks itself with probability  $\frac{1}{2d(v)}$ , where  $d(v)$  is the current degree of  $v$ .
- 2: If no higher degree neighbour of  $v$  is also marked, node  $v$  joins the MIS. If a higher degree neighbor of  $v$  is marked, node  $v$  unmarks itself again (If the neighbors have the same degree, tries a broken arbitrarily, *e.g.*, by identifier).
- 3: Delete all nodes that joined the MIS and their neighbors, as they cannot join the MIS anymore.

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## Theorem 7.11 (Analysis of Algorithm 7.6)

Algorithm 7.6 terminates in expected time  $O(\log n)$

# Fast MIS terminates in expedited time $O(\log n)$

$d(v)$ : node degree of  $v$

$N(v)$ : set of neighbors of  $v$

$H(v)$ : set of neighbors of  $v$  with higher degree ...

$M$ : set of nodes marked in Step 1.

# Fast MIS terminates in expedited time $O(\log n)$

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$$\begin{aligned} P[v \notin \text{MIS} | v \in M] &= P[\text{there is a node } w \in H(v), w \in M | v \in M] \\ &= P[\text{there is a node } w \in H(v), w \in M] \\ &\leq \sum_{w \in H(v)} P[w \in M] = \sum_{w \in H(v)} \frac{1}{2d(w)} \\ &\leq \sum_{w \in H(v)} \frac{1}{2d(v)} \leq \frac{d(v)}{2d(v)} = \frac{1}{2} \end{aligned}$$

Then

$$P[v \in \text{MIS}] = P[v \in \text{MIS} | v \in M] \cdot P[v \in M] \geq \frac{1}{2} \cdot \frac{1}{2d(v)}$$



## Fast MIS terminates in expedited time $O(\log n)$

### Lemma 7.8(Good Nodes).

A node  $v$  is called good if

$$\sum_{w \in N(v)} \frac{1}{2d(w)} \geq \frac{1}{6}$$

where  $N(v)$  is the set of neighbors of  $v$ . Otherwise we call  $v$  a bad node. **A good node will be removed in Step 3 with probability  $p \geq \frac{1}{36}$ .**

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### Lemma 7.9(Good Edges).

An edge  $e = (u, v)$  is called bad if both  $u$  and  $v$  are bad; else the edge is called good. The following holds:**At any time at least half of the edges are good**

## Fast MIS v2

The algorithm operates in synchronous rounds, grouped into phases.

**A single phase** is as follows:

**ALGORITHM 7.12:** FAST MIS v2()

- 1: Each node  $v$  chooses a random value  $r(v) \in [0, 1]$  and send it to its neighbors.
- 2: if  $r(v) < r(w)$  for all neighbors  $w \in N(v)$ , node  $v$  enters the MIS and informs its neighbors.
- 3: if  $v$  or a neighbor of  $v$  entered the MIS,  $v$  terminates ( $v$  and all edges adjacent to  $v$  are removed from the graph), otherwise  $v$  enters the next phase.

**Corollary 7.18**(Running Time of Algorithm 7.12)

Algorithm 7.12 terminates *w.h.p.* in  $O \log n$  time.

# Application for Matching

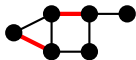
## Definition 7.19 (Matching)

Given a graph  $G = (V, E)$  a matching is a subset of edges  $M \subseteq E$ , such that no two edges in  $M$  are adjacent (*i.e.*, where no node is adjacent to two edges in the matching). A matching is **maximal** if no edge can be added without violating the above constraint. A matching is **maximum** cardinality is called maximum. A matching is called **perfect** if each node is adjacent to an edge in the matching

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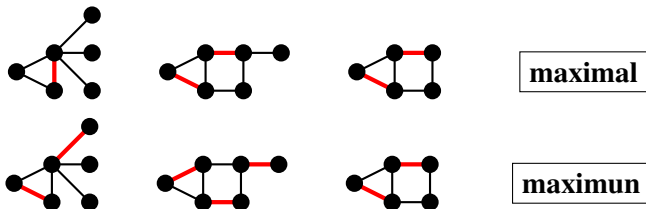


maximal

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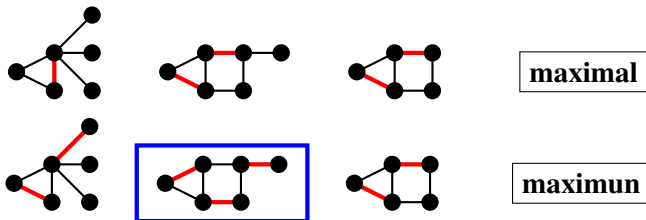
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# Application for Matching

- In contrast to MaxIS, a maximum matching can be found in polynomial time and also easy to approximate, since any maximal matching is a 2-approximation.
- An independent set algorithm is also a matching algorithm: Let  $G = (V, E)$  be the graph for which we want to construct the matching. The so-called line graph  $G'$  is defined as follows: for every edge in  $G$  there is a node in  $G'$ ; two nodes in  $G'$  are connected by an edge if their respective edges in  $G$  are adjacent. A (maximal) independent set in the line graph  $G'$  is a (maximal) matching in the original graph  $G$ , and vice versa. Using Algorithm 7.12 directly produces a  $O(\log n)$  bound for maximal matching.



## Application for Coloring

### ALGORITHM 7.20 GENERAL GRAPH COLORING()

- 1: Given a graph  $G = (V, E)$  we virtually build a graph  $G' = (V', E')$  as follows:
- 2: Every node  $v \in V$  clones itself  $d(v) + 1$  times ( $v_0, \dots, v_{d(v)} \in V'$ ),  $d(v)$  being the degree of  $v$  in  $G$ .
- 3: The edge set  $E'$  of  $G'$  is as follows:
- 4: First all clones are in a clique:  $(v_i, v_j) \in E'$ , for all  $v \in V$  and all  $0 \leq i \leq j \leq d(v)$ .
- 5: Second all  $i^{\text{th}}$  clones of neighbors in the original graph  $G$  are connected:  $(u_i, v_i) \in E'$ , for all  $(u, v) \in E$  and all  $0 \leq i \leq \min(d(u), d(v))$ .
- 6: Now we simply run (simulate) the fast MIS algorithm 7.12 on  $G'$ .
- 7: if node  $v_i$  is in the MIS in  $G'$ , then node  $v$  gets color  $i$ .

# Application for Coloring

## **Theorem 7.21**(Analysis of Algorithm 7.20).

Algorithm 7.20  $(\Delta + 1)$ -colors an arbitrary graph in  $O(\log n)$  time, with high probability,  $\Delta$  being the largest degree in the graph.

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## Theorem 7.21 (Analysis of Algorithm 7.20).

Algorithm 7.20  $(\Delta + 1)$ -colors an arbitrary graph in  $O(\log n)$  time, with high probability,  $\Delta$  being the largest degree in the graph.

Proof: Thanks to the clique among the clones at most one clone is in the MIS. And because of the  $d(v) + 1$  clones of node  $v$  every node will get a free color! The running time remains logarithmic since  $G'$  has  $O(n^2)n$  nodes and the exponent becomes a constant factor when applying the logarithm.

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- Together with Corollary 7.5 we get quite close ties between  $(\Delta + 1)$ -coloring and the MIS problem.
- Computing a MIS also solves another graph problem on graphs of bounded independence.

## Application for Dominating Sets

### Definition 7.22(Bounded Independence).

$G = (V, E)$  is of bounded independence, if for every node  $v \in V$  the largest independent set in the neighborhood  $N(v)$  is bounded by a constant.

### Definition 7.22((Minimum) Dominating Sets).

A dominating set is a subset of the nodes such that each node is in the set or adjacent to a node in the set.

A minimum dominating set is a dominating set containing the least possible number of nodes.

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A dominating set is a subset of the nodes such that each node is the set or adjacent to a node in the set.

A minimum dominating set is a dominating set containing the least possible number of nodes.

- In general, finding a dominating set less than a factor  $\log n$  larger than a minimum dominating set is NP-hard.
- Any MIS is a dominating set: if a node was not covered, it could join the independent set.
- In general a MIS and a minimum dominating set have not much in common (think of a star). For graphs of bounded Independence, this is different.

# Application for Dominating Sets

## Corollary 7.24.

On graphs of bounded independence, a constant-factor approximation to a minimum dominating set can be found in the time  $O(\log n)$  *w.h.p.*

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Proof: Denote by  $M$  a minimum dominating set and by  $I$  a MIS. Since  $M$  is a dominating set, each node from  $I$  is in  $M$  or adjacent to a node in  $M$ . Since the graph is of bounded independence, no node in  $M$  is adjacent to more than constantly many nodes from  $I$ . Thus,  $|I| \in O(|M|)$ . Therefore, we can compute a MIS with Algorithm 7.12 and output it as the dominating set, which takes  $O(\log n)$  rounds *w.h.p.*



## References

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